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This paper is devoted to the solution of the problem of freight car wheel wear reduction on 1520 mm gauge railways (the former USSR). The paper gives a brief description of the comprehensive retrofit of standard freight-car trucks (model 18-100) proposed at the Institute of Technical Mechanics of the National Academy of Sciences of Ukraine and the State Space Agency of Ukraine (ITM of NASU and SSAU) and introduced on the Ukrainian railways. The retrofit involves the use of US companies' devices adapted to the former USSR's countries and the ITM-73 wear-resistant wheel profile specially developed at the ITM of NASU and SSAU; it offers a several-fold increase in the life of critical running gear assemblies and makes it possible to reduce wheel and rail contact wear by a factor of 2–2.5.

The aim of the work was to refine the comprehensive retrofit of freight-car trucks, namely, to develop new

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$$B_j(x) = \sum_{i=1}^{n_j} a_{ji} \cdot \sin(2\pi \cdot x / l_{ji}), \quad j = 1, 4,$$

x –

;  $n_j$  –

;  $a_{ji}$  –  $l_{ji}$  –

$a_{ji}, l_{ji} \quad n_j \quad (j = 1, 4, i = 1, n_j)$

[19, 20].

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[21 - 23]

[24]

$\theta_{ws}$ ,  $\Delta y$ ,  $f_W(y)$ ,  $f_R(y)$ ,  $D(y) = f_R(y) - f_W(y)$ ,  $\Delta z$ ,  $\chi$ ,  $\gamma$  (6)

[25]:

$$T = -F\varepsilon \left[ \left( \frac{F\varepsilon}{\mu N} \right)^m + 1 \right]^{-\frac{1}{m}},$$

$$F = 350m\sqrt{Nr},$$

$$m = 3,5,$$

$T = \varepsilon \dots$ ;  $N = \dots$   
 $\dots$ ;  $r = \dots$   
 $\alpha$   $\Psi_{ws}$ :

$$\varepsilon = (\varepsilon_\psi^2 + \varepsilon_\alpha^2)^{1/2} = [(\varepsilon_x \sec \Psi_{ws})^2 + (\varepsilon_y \sec \alpha)^2]^{1/2},$$

$\varepsilon_x, \varepsilon_y = \dots$

$$T_\psi = \frac{\varepsilon_\psi}{\varepsilon} T, \quad T_\alpha = \frac{\varepsilon_\alpha}{\varepsilon} T.$$

$$N = N_z \sec \alpha,$$

$N_z = \dots$

$$\begin{cases} N_1 \cos \alpha_1 + N_2 \cos \alpha_2 = N_z \\ N_1 \sin \alpha_1 + N_2 \sin \alpha_2 = N_y \end{cases} \quad (1)$$

$N_y = \dots$

$$N_y = N_z \Delta z'; \quad \Delta z' = \frac{\Delta z}{\Delta y}; \quad \alpha_1, \alpha_2 = \dots$$

(1)

$$N_1 = \frac{N_z (\operatorname{tg} \alpha_2 - \Delta z')}{(\cos \alpha_1 \operatorname{tg} \alpha_2 - \sin \alpha_1)}, \quad N_2 = \frac{N_z (\operatorname{tg} \alpha_1 - \Delta z')}{(\cos \alpha_2 \operatorname{tg} \alpha_1 - \sin \alpha_2)}.$$

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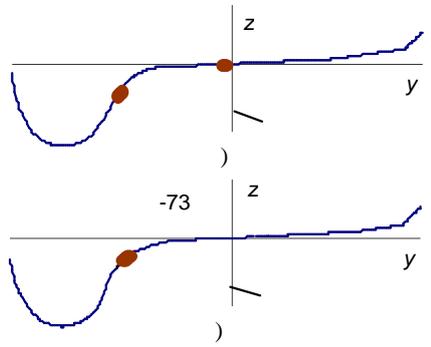
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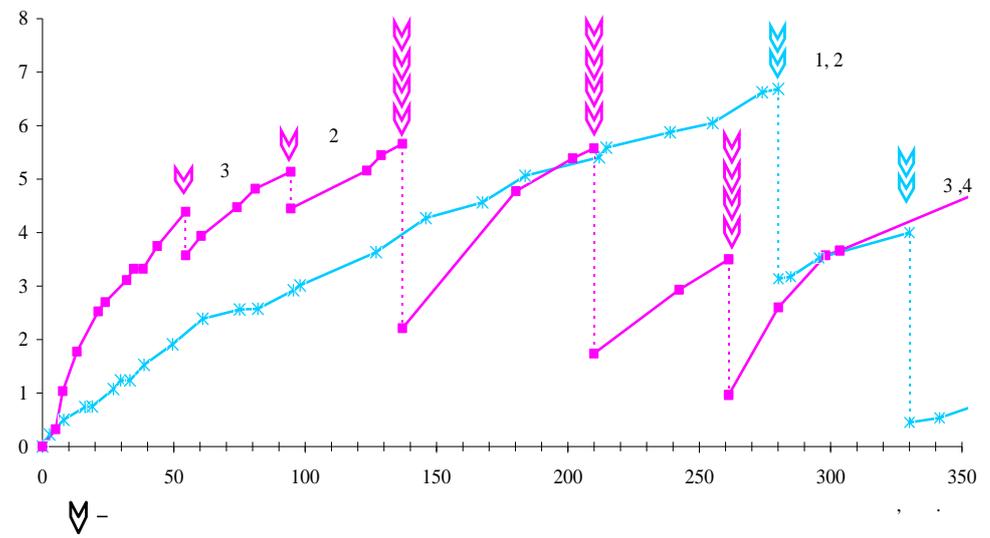
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$$f_W(y) = f_R(y) \cdot \Delta y \cdot \theta_{ws} \cdot \psi_{ws}$$

$k$

$$T_{\psi k} = \frac{\varepsilon_{\psi k}}{\varepsilon_k} T_k, \quad T_{\alpha k} = \frac{\varepsilon_{\alpha k}}{\varepsilon_k} T_k.$$

$$T_x = \sum_{k=1}^n T_{\psi k} \cos \psi_{ws}, \quad T_y = \sum_{k=1}^n T_{\alpha k} \sin \alpha_k,$$

$n$

$N_z$

$N_z$

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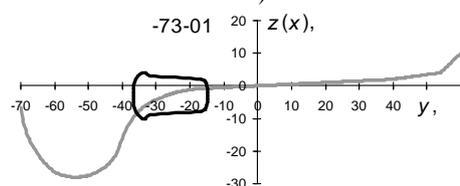
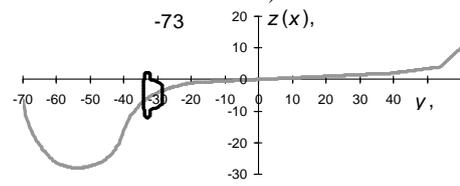
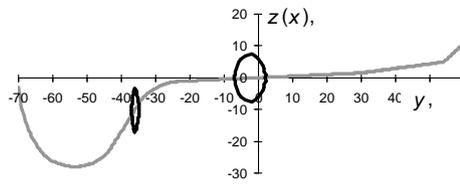
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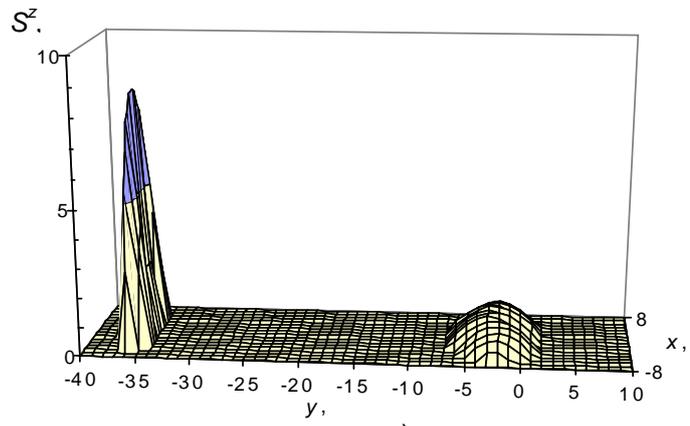
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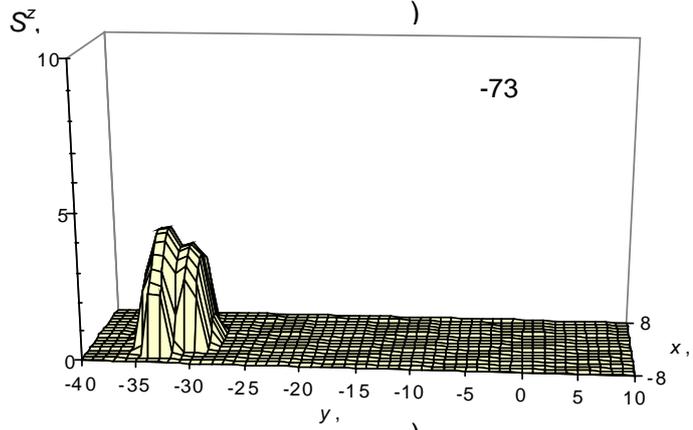
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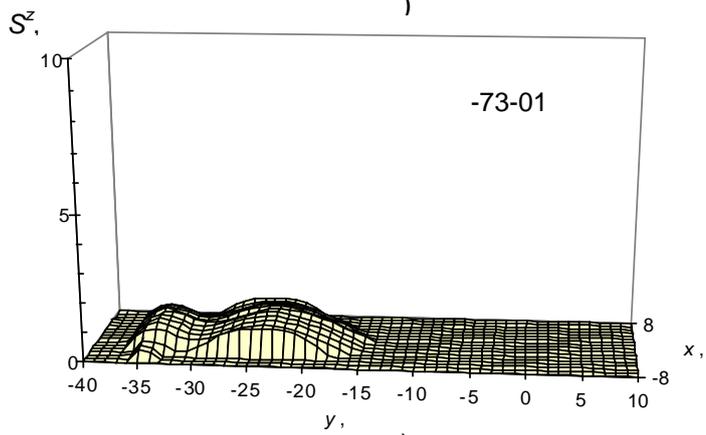
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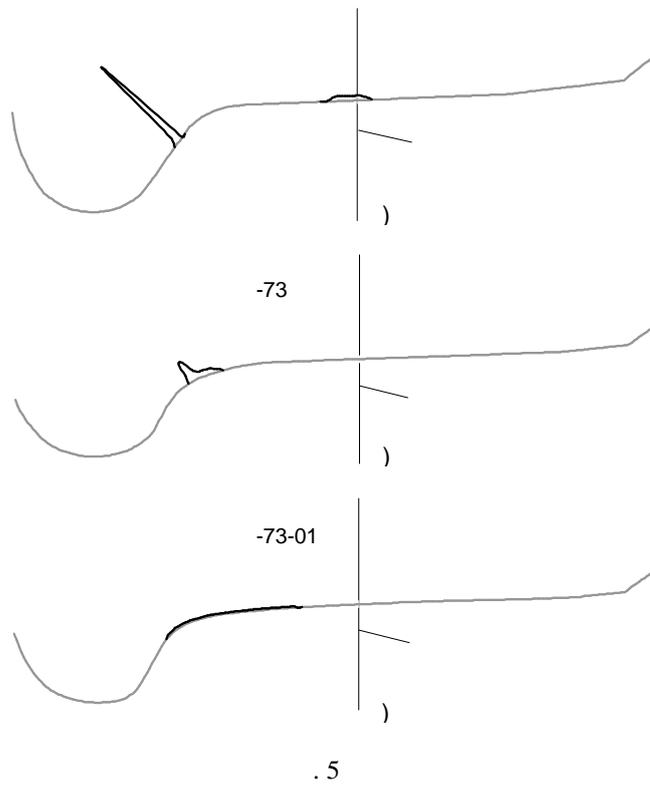


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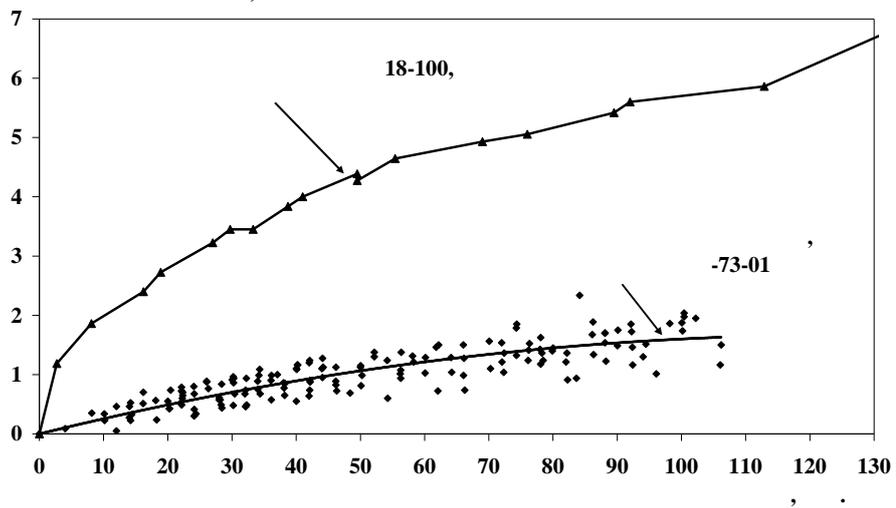


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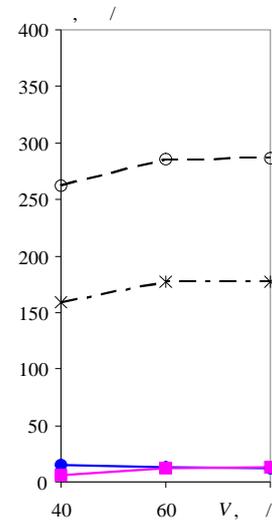
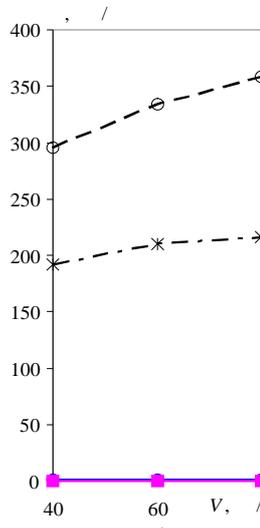
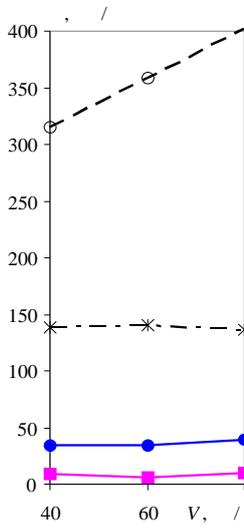
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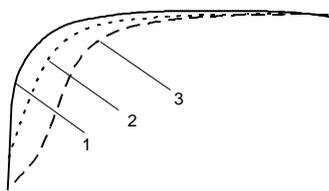


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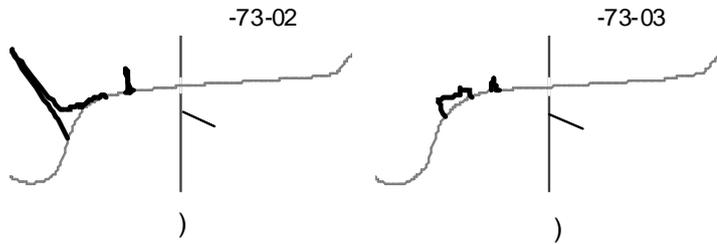
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