## YE. N. TACHININA

## CONDITIONS OF OPTIMAL TRAJECTORY FOR CONSTELLATION OF NANOSATELLITES INJECTED BY AEROSPACE SYSTEM

National Aviation University 1, Cosmonaut Komorov Avenue, 03058, Kiev, Ukraine, -mail: tachinina@rambler.ru

The paper deals with the determination of the conditions for constructing an optimal launch trajectory for the nanosatellite constellation injected by the aerospace system. These conditions satisfy both the main and alternative requirements for optimal trajectories, as well as use efficiently the power resources of an integrated dynamic system. The methods of mathematical modeling, variation calculations, optimal control, and numerical integration are applied.

The paper proposes the method for building the optimal trajectories of an integrated dynamic system. It includes the enhancing concept applied to not only the optimization criterion and the phase state vector of a launch vehicle, but to limitations imposed on the trajectories of the separated head rockets as well. This method satisfies both the basic and alternate requirements for optimal trajectories.

It is concluded that the proposed method allows replacing the initial problem of the complex-limitations optimization with other simpler problem wherein cross couplings are excluded. In this case, the solution of this problem satisfies given requirements and coincides with the solution of the initial problem.

**Keywords:** *integrated dynamic system, optimization, trajectory, nanosatellites.* 

- 1. Ashchepkov L. T. Optimal Control of Shock Systems. Novosibirsk: Nauka, 1987. 226 p.
- 2. Sage E.P., White Ch. S. Optimal Control of Systems. M.: Radio i Svayaz, 1982. 392 p.
- 3. Brayson A., Cho Yu-Shi. Applied Theory of Optimal Control. M.: Mir, 1972. 554 p.
  - Lysenko A. I. Optimization of trajectory of integrated dynamic system with current moment of separation.
- Tekhnicheskaya Kibernetika. Kiev: Vysshaya Shkola, 1990. Issue 14. P. 24 31. *Lysenko A. I.* Model problem for selecting optimal program of motion of transportation system. Avtomatika.
- 1988. No 6. P. 62 64. 5. *Lysenko A. I.* Simulation of optimal motion of integrated system. Electronnoe Modelirovanie. 1989. Vol. 11
- Lysenko A. I. Simulation of optimal motion of integrated system. Electronnoe Modelirovanie. 1989. Vol. 11 No 4. P. 80 – 83.
- Lysenko A. I. Necessary conditions of optimal trajectory of integrated dynamic system. Aviation instruments, navigation systems of astronaut crew life support. M.: Zhukovsky Air Force Engineering Academy, 1988. P. 82 – 95.
- Lysenko O. I., Tachynina O. M., Chumachenko S. M., Nikulin O. F. Statement of the problem of branched trajectories theory application to resolve S&R problems in emergency zone. Tekhnicheskaya Mekhanika. 2015. No 1. P. 73 – 78.
- D. Tachinina O, Zacharchenko V., Lysenko O., Alekseeva I. The optimal injection path of group of nanosatellite multisensor-based platforms. IEEE 4th International Conference on Methods and Systems of Navigation and Motion Control (Kyiv, Ukraine, October 18–20, 2016). .: NAU, 2016. . 155 – 158.
- Tachinina O., Gusynin A., Lysenko O., Chumachenko S. The method of injection of earth remote monitoring subminiature satellites with the aid of flying space launch facility based on AN-124-100 and AN-225 airplanes. IEEE 4th International Conference on Methods and Systems of Navigation and Motion Control (Kyiv, Ukraine, October 18–20, 2016). .: NAU, 2016. . 200 – 205.
- Tachinina O., Lysenko O., Chumachenko S. The system of injection of subminiature satellites (nanosatellites) to near-Earth orbit based on N-124-100 airplane. 10th International Scientific Conference on Modern Challenges in Telecommunications and 8th International Scientific Conference of Under-Graduate and Graduate Students on Prospects for Development of Information-Telecommunication Technologies and Systems (Kyiv, Ukraine, April 19-22, 2016). .: KPI, 2016. . 477 450.