

2)

3)

4)

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() - 12 - 15 ,
 () , 3 - 5 ;
 () - 25 - 30 ,
 - 5 - 8 .

5)

1.

$$= \sum_{t=1}^T \frac{(t) - (t)}{(1 + \delta)^t},$$

$$I = \text{---},$$

$$T \quad (T) = \sum_{t=1}^T (t),$$

$$\sum_{t=1}^n \frac{\text{---}}{(1 + \text{---})^t} = 0,$$

: t - ; T -
 ; (t) - ; (t) -
 ; δ - ; -
 (T) - ; n -

(Z_{CZ})
 (μ_{CZ})

$$Z_{CZ} = f(T_p, E_p, \mu_{CZ}) \rightarrow \min, \mu_{CZ} \geq b, k_{TU} \geq c.$$

$$\mu_{CZ} = f(T_p, E_p) \rightarrow \max, Z_{CZ} \leq Z_o, k_{TU} \geq c,$$

$Z_{CZ} -$; $T_p, E_p -$

; $\mu_{CZ} -$ ()

; $b -$

; $Z_o -$

; $k_{TU} -$

; $c -$

:

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- () ;

- () ;

- () ;

$$= \langle W, Z, T, R \rangle, \quad (1)$$

$$W = \langle W_1, W_2 \rangle, R = \langle R_1, R_2 \rangle, W_1 = \frac{E}{Z}, W_2 = k,$$

$W -$; $Z -$; $T -$;
 ; $R -$;

$R_1 -$; $R_2 -$;
 ; $W_1 -$ () ;

); $W_2 = k$ - -
 -
 ;

$E -$

$W R .$
 W

R

[6, 7].

-
 - () ();
 - ();
 - ();
 - ();
 - ();
 - ().

$$= \langle \dots \rangle.$$

(UP), (T), $\{\tau_i\}$,
 ()
 (k_T)

$$= F(\{\tau_i\}, UP, T, k).$$

()
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[1].

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 (1),

$$k = \frac{+ +}{-};$$

$$I = \frac{-}{\cdot(1-\eta)};$$

$$k = \alpha \cdot k ,$$

; η -

; α -

; k -

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$\eta \approx 0,$

(1)

[2, 5, 8].

$\eta \approx 1,$

(1)

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2.

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[3].
, , .

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$$\begin{aligned}
 Z(t_0) &= Z(t_0) \cdot k, \\
 Z &= Z(t_0) \cdot [f(k) \cdot (\alpha_1 + \alpha_2 + \alpha_3 \cdot k) + 1] + Z(t_0), \\
 Z(t_0) &= Z(t_0) \cdot (q(k_X) - 1), \\
 k &= \exp(\alpha \cdot f(k) \cdot k) \cdot \exp(\beta \cdot \frac{-}{1-}),
 \end{aligned}$$

$$\begin{aligned}
 k &= \prod_{i=1}^I (\frac{\tau}{\tau})^{\gamma_i}, \quad \sum_{i=1}^I \gamma_i = 1, \\
 f(k) &= q_1(\exp(q_2 \cdot k) - 1), \\
 g(k) &= \exp \gamma \cdot (k - 1),
 \end{aligned}$$

Z(t_0) -

t_0; Z(t_0) -
t_0

; k -

, k ∈ (0-1); k -

; Z -

; α_1, α_2, α_3 -

; k -

; k -

; Z(t_0) -

; Z(t_0) -

$t_0; \tau, \tau -$

$; \gamma_i -$

$(); \alpha, \beta, q_1, q_2, \gamma -$

$i -$

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$(k),$

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$(k),$

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$(k , k).$

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$$Z = F(Z_a, k , k , k , k)$$

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$[2, 8].$

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$$\sigma = \sqrt{\sum_{j=1}^n (q_j \cdot \frac{1-\delta_j}{3})^2} \cdot \sqrt{\alpha_T \cdot \frac{\Delta T}{T} + 1}, \quad q_j = \frac{\partial Z}{\partial p_j},$$

$q_j =$

$j =$

$;\delta_j =$

$;\alpha_T =$

$(\dots); \Delta T =$

$;\ T =$

$;\ q =$

(R_2) .

$R, P :$

$$R = (\dots) - (\dots^*), \quad P \approx \frac{N_1(\dots, \dots^*)}{N},$$

$R =$

$(\dots); (\dots^*) -$

(\dots)

$(\dots^*) -$

$(\dots) -$

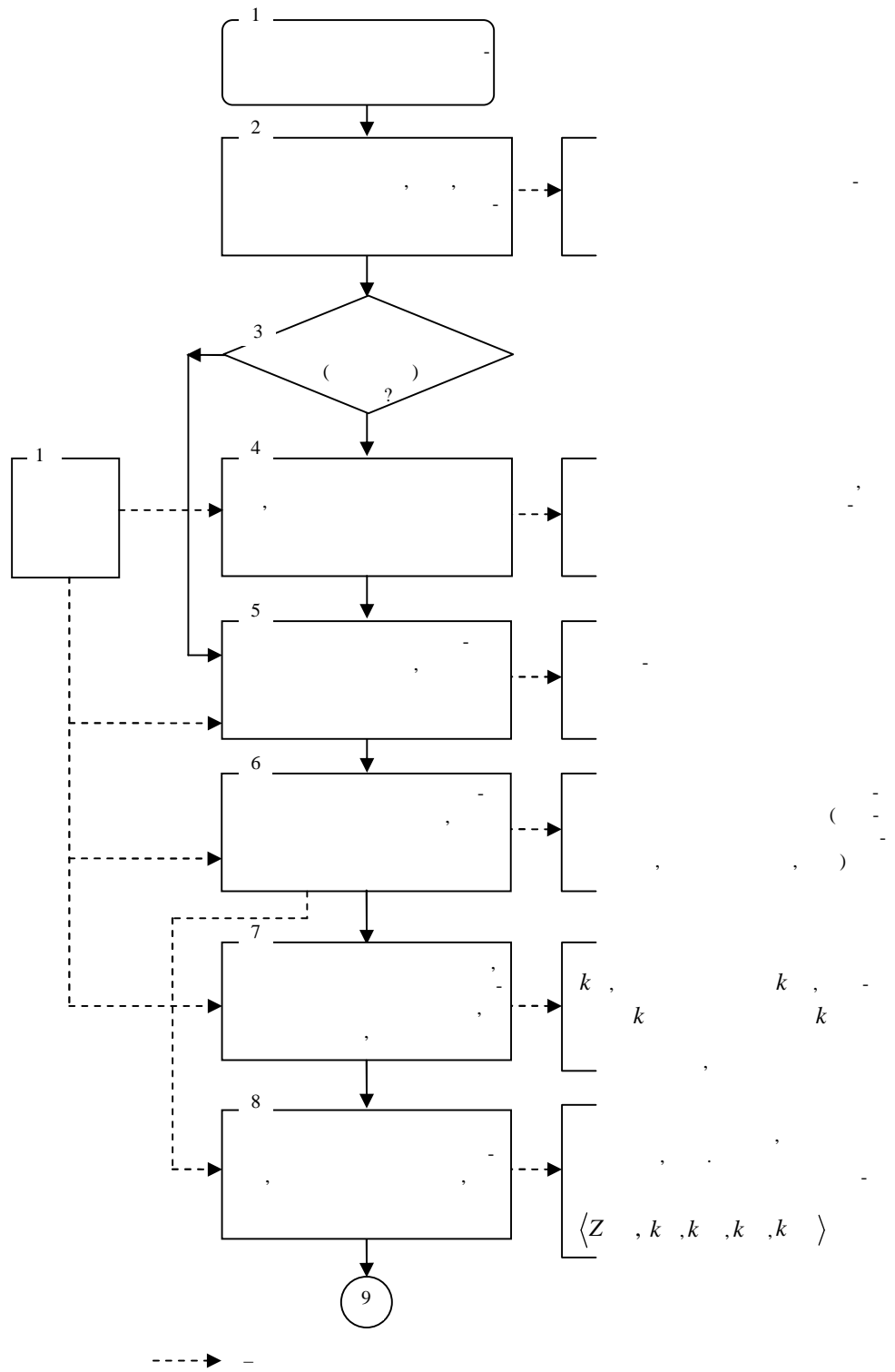
$N_1(\dots, \dots^*) -$

$|R| \leq Q ; N =$

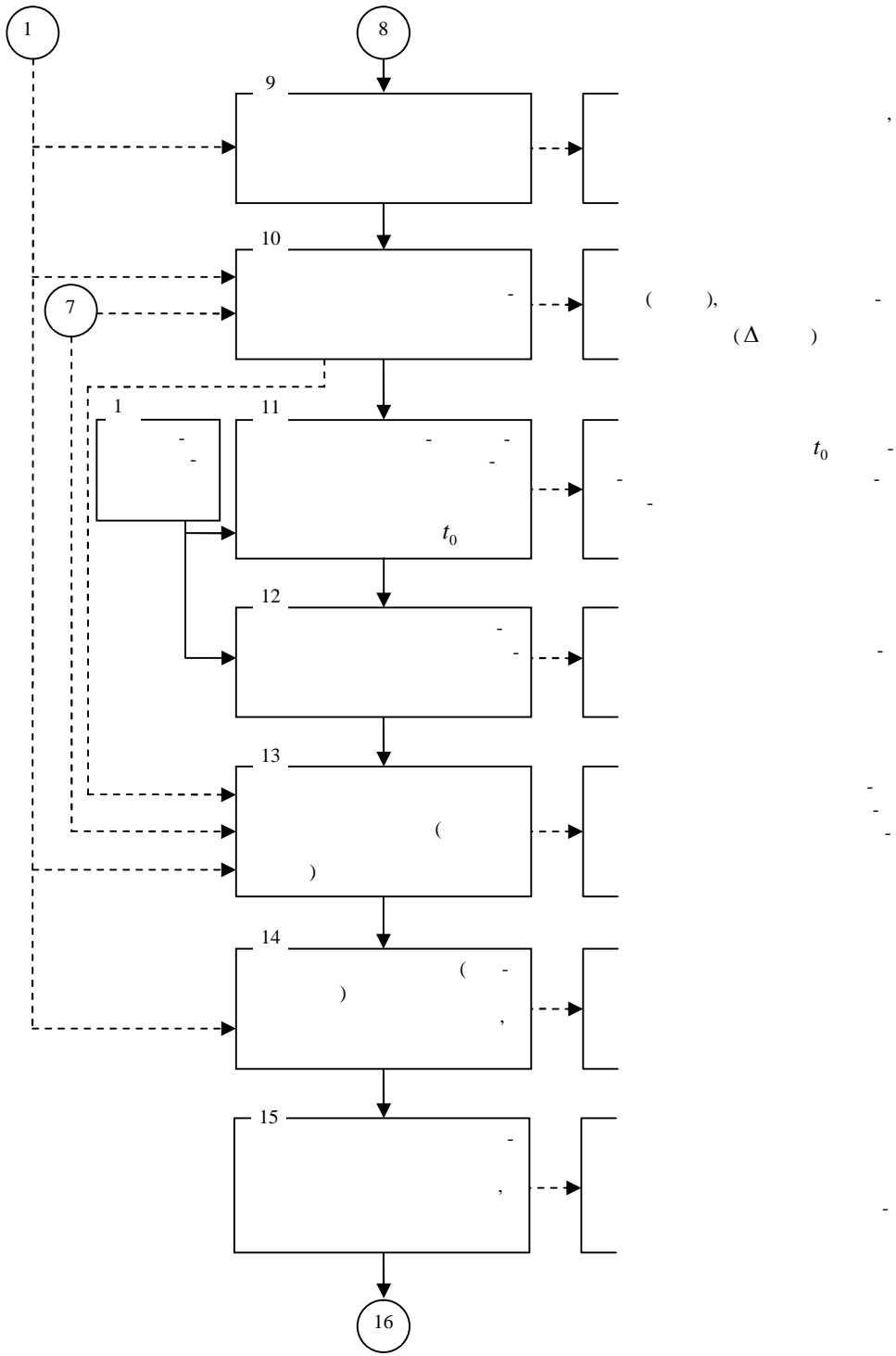
$;\ Q =$

5.

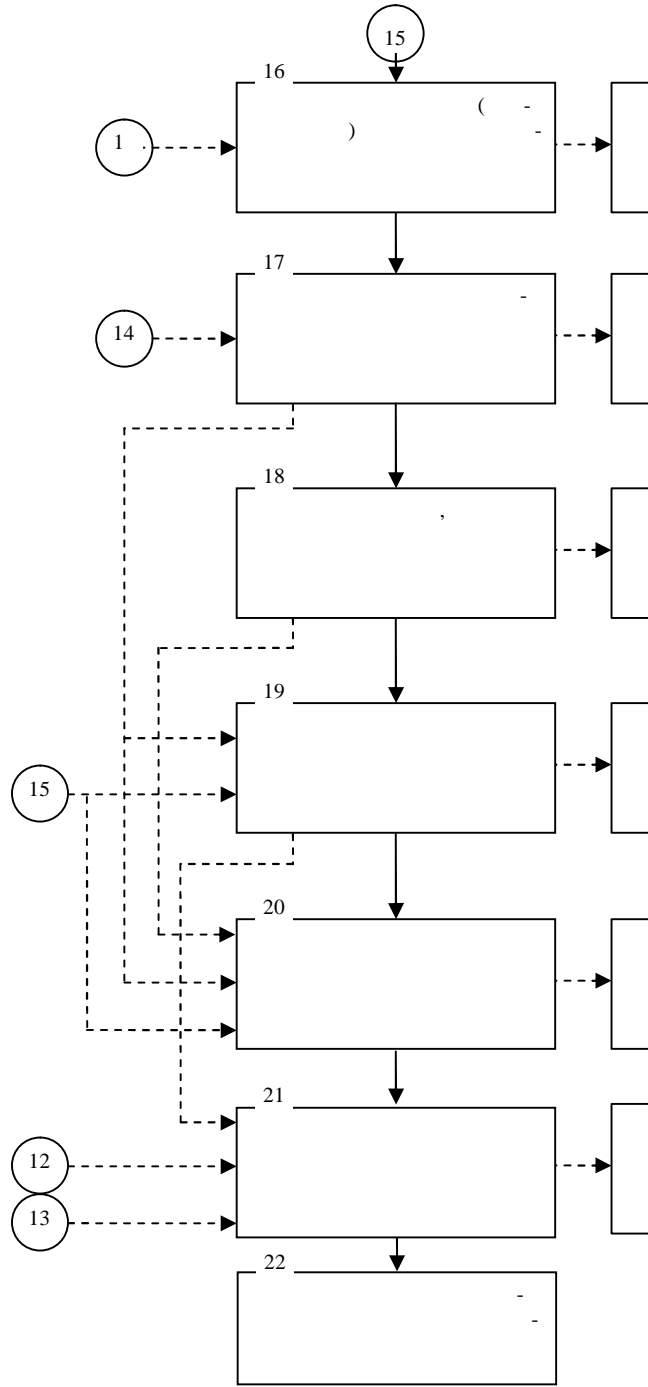
.1



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.1, 2



. 1, 3

1. - -
 2. - -
 3. - -
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26.03.2015,
 17.06.2015